

# AMR sensor array design for permanent magnet 3D motion tracking



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### Introduction

Magnetic field sensors are essential components of several industrial, biomedical and consumer electronics applications. Sensors based on the anisotropic magnetoresistance (AMR) effect are particularly attractive due to their relatively simple and cheap fabrication process, which makes them easily prone to miniaturization thus allowing to achieve high sensitivity at low cost in a compact footprint. Here, we combine numerical methods and analytical calculations to design AMR sensor arrays capable of tracking the 3D motion of a permanent magnet.

## Integration of magnets and magnetic sensors into microsystems

The basic structure of this class of microsystems consists of two main parts: (i) an array of AMR sensors and (ii) a permanent magnet embedded within a deformable membrane and therefore capable of moving relative

to the magnetic sensors as a result of the external solicitation generated by the physical observable of interest.

The concept can be applied for a wide spectrum of sensing solutions: tactile and pressure sensors, accelerometers, (micro-)flow sensors, etc.



#### **AMR sensors**

Resistance change in a ferromagnetic material according to the relative orientation of current and magnetization:  $R = R_0(1 + \Delta r_{max} \cos^2 \theta)$ 



#### Sensor response:

#### • ferromagnetic (i.e., NiFe) stripe



## Magnetic microsystem design

AMR sensor array design combines numerical simulations and analytical calculations.



Different AMR sensor array layout solutions for 1D, 2D and 3D magnet motion reconstruction are explored.







*8*0.6 arber pole 0 50 H (Oe) -50

Current is forced at 45  $^{\circ}$  with respect to the easy axis and the AMR response is linearized

Stripe magnetic properties (and therefore AMR response) can be tuned by varying the geometry.



## **AMR sensor fabrication**

AMR sensor patterning via laser lithography and material deposition via e-beam evaporation.





## **Magnet integration concepts**

#### **First approach**

- Flexible polymer (e.g., PDMS) membrane
- off-the-shelf of sub-mm Integration permanent magnets into the membrane
- Assembly of deformable membrane and AMR magnetic sensor into a single device

#### Second approach

Integration of microfabricated permanent magnets into the deformable membrane





N. Dempsey et al, Appl. Phys. Lett. 90 (2007) 092509

0,51908 0,51908 0,4542 0,38931 0,32443 0,25954 0,19466 0,12977 0,064886

#### Limitations

- Large fabrication tolerances
- Poor control over magnet properties (size, magnetization)



- Fine control of magnet properties
- Low fabrication tolerances
- Scalability potential
- Suitable for extension to several other MEMS systems

Direct Write Lithography Heidelberg DWL66+

Thin Film Deposition SEM/EDX/FIB/EBL Leybold UNIVEX 900 FEI Helios G4 UC

## Conclusions

These results demonstrate the possibility to track the 3D movement of a permanent magnet properly designed and monolithically via fabricated planar arrays of AMR sensors. The versatility of the concept presented here holds potential for the realization of a broad spectrum of easy-to-fabricate, low-cost and miniaturized sensors suitable for probing a wide variety of physical observables.

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Thin Film Technologies erging materials advanced niconductor and croelectronic ustries	Integrated Photonics Technologies Design, modelling and fabrication of integrated photonics, Photonic MEMS and meta- optics for miniature sensing and imaging systems	Magnetic Microsystem Technologies Analytical modeling, combination of micro & macro magnetic simulations, AMR sensor design and fabrication	Piezoelect Microsyste Technolog RF filters, SAW/BAW, pie MEMS, PMUTS MOEMS, micromirrors, microphones, microspeakers
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